Gas-Mediated Impact Dynamics in Fine-Grained Granular Materials

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Noncohesive granular media exhibit complex responses to sudden impact that often differ from those of ordinary solids and liquids. We investigate how this response is mediated by the presence of interstitial gas between the grains. Using high-speed x-ray radiography we track the motion of a steel sphere through the interior of a bed of fine, loose granular material. We find a crossover from nearly incompressible, fluidlike behavior at atmospheric pressure to a highly compressible, dissipative response once most of the gas is evacuated. We discuss these results in light of recent proposals for the drag force in granular media.

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Studies of the impact of solid objects into granular beds have a long history, with first systematic work dating back to the 18th century [1,2]. The topic reemerged in the 1960s with attempts to characterize the strength of the lunar surface [3,4] and, recently, with investigations of cratering [5–13] and granular jet formation [14–17]. One unresolved issue remains the form for the drag force experienced by the impacting solid as it moves through the granular medium. Various competing force laws have been proposed, based on scaling laws relating the penetration depth to the impact energy or momentum [5,6], or on direct measurement of the trajectory of the impacting object [7–11]. However, none of these take into account the interaction between the solid grains inside a granular bed and the surrounding gas.

This interaction is known to play a significant role in many situations where the bed is externally forced, especially for small grain sizes, when the bed's gas permeability becomes sufficiently low to sustain a pressure gradient that can compete with the weight of the material. The resulting feedback between grain motion and ambient gas flow gives rise to complex dynamics not only when a bed is fluidized by direct gas injection [18], but also in many vibrated granular systems [19–22]. There have been indications that the morphology of craters differs for small grain sizes due to interstitial gas flows [13]. Also, for fine powders, the size and shape of granular jets ejected upward after impact was found to depend on the presence of interstitial gas [16]. However, with one exception [17], the role of gas-grain interactions in determining the trajectory of impacting solids has not been investigated in detail. Here we demonstrate that ambient gas inside a granular bed strongly affects the impact dynamics and show how this alters the drag force in a fine-grained granular medium.

Previous experiments used either two-dimensional (2D) setups [11] or indirect methods to gauge the motion of a projectile inside a 3D bed [5–10]. In contrast, our approach is based on high-speed x-ray imaging which gives direct, time-resolved access to the dynamics in the bed interior and also allows us to extract local changes in the bed packing density.

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For the experiments reported here, a steel sphere (diameter $D_s = 12$ mm) was dropped from a height of 0.34 m into an 85 mm deep bed of boron carbide (B₄C) particles (50 μ m average diameter). B₄C, which is nonspherical, was chosen to optimize the x-ray transmission; separate experiments, studying jet formation in a variety of different media, indicate that grain shape is not a critical parameter [16,23]. The bed was contained in a cylindrical tube with 35 mm inner diameter. Before each drop the bed was aerated by dry nitrogen entering through a diffuser built into the bottom of the container. By slowly turning off the nitrogen flow, the packing fraction $\phi = V_g/V_{\rm tot}$, where V_g is volume occupied by grains and V_{tot} is the total volume of the bed, was adjusted before each drop to a value around 0.5. The system could be sealed and evacuated down to pressures as low as 0.7 kPa. The pump speed was limited to prevent air flow from disturbing the loose packing. We checked for electrostatic charging by performing experiments in air at a high humidity (\sim 50%) where electrostatic effects typically vanish [24] and observed no qualitative change in the impact dynamics.

X-ray imaging was performed at the GSECARS beam line at the Advanced Photon Source using a high intensity beam with energy width 5 keV centered at 22 keV. X-ray transmission through the bed was imaged off a phosphor screen at 6000 frames per second using a Phantom v7 video camera. The beam size restricted the field of view to 22 mm \times 8.7 mm sections of the bed. To capture the dynamics across the full vertical extent of the bed, movies of multiple independent drops, imaged at different, slightly overlapping vertical bed positions, were stitched together using the impacting sphere to align them horizontally and synchronize them.

The measured intensity I is a function of the product $\rho \phi l$. Here ρ is the density of the grain material and l the x-ray path length through the bed, determined from the cylindrical geometry of the setup. To correct for spatial variations in beam intensity and camera sensitivity, calibration curves relating I to the packing fraction ϕ were calculated for each of the 780×300 pixels in the field of view [23]. Across each frame in a single movie, initial

packing fraction ϕ_0 varied by about 1%, indicating a uniform bed packing prior to impact. From drop to drop ϕ_0 varied between 0.49 and 0.52. This variation was present at atmospheric pressure, where the pump was disconnected, as well as at reduced pressure, indicating that it was due to small, unavoidable differences in bed settling after fluidization, but not due to the evacuation of the chamber.

X-ray images of the interior reveal a striking air pressure dependence of both bed and sphere dynamics (Fig. 1). At atmospheric pressure (P = 101 kPa), the sphere easily penetrates the bed, reaching the bottom of the system and opening up a large cylindrical hole. This hole closes first at some intermediate depth, resulting in a crater near the top and a gas-filled cavity behind the sphere. Both of these region then fill in from the sides due to gravitational pressure. This process has previously been identified as driving jet formation [15,16], but the role of the interstitial gas has remained controversial [17]. At P = 12 kPa the overall features are still similar to those at atmospheric conditions, but the dynamics begin to change. The cavity is smaller, and while the top surface of the bed still rises to compensate for the change in bed volume, it does not rise quite as high [Figs. 1(a)-1(c)]. Further reducing the pressure to 0.7 kPa significantly changes the dynamics. The bed barely rises, and there is significant compaction in front of the sphere, evident in the darker region under the sphere in

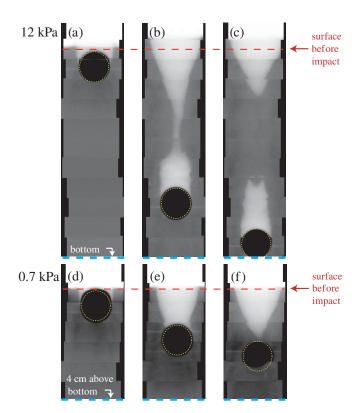


FIG. 1 (color online). Pressure dependence of impact dynamics. Composite x-ray images at 12 kPa (a) 5 ms, (b) 40 ms, and (c) 57 ms after impact. Images at 0.7 kPa (d) 5 ms, (e) 12 ms, and (f) 28 ms after impact.

Figs. 1(d)-1(f). As a consequence, the sphere is able to penetrate only a short distance and the hole closes directly above the sphere without forming a separate cavity.

To quantify this change in impact dynamics we plot in Fig. 2(a) the position of the bottom of the sphere, $z_s(t)$, as it moves through the bed. At $P=101\,$ kPa the sphere hits the bottom with sufficient momentum to bounce back up a bit; at $P=8.7\,$ kPa and below the sphere is stopped well before reaching the bottom. From $z_s(t)$ we compute $v_s=dz_s/dt$ [Figs. 2(b) and 2(c)]. With deceasing ambient pressure there is a monotonic decrease in penetration depth and an increase in bed resistance.

Inside the bed the net force on the impacting projectile is the sum of its weight, -mg, and a drag force, F_d , representing the bed resistance. Models for this resistance are of the form $F_d = F_C + c |v_s|^{\beta}$, where F_C represents Coulomb friction and c characterizes the strength of the velocity-dependent drag. Specific forms include $F_C = \text{const}$ with $\beta = 1$ [5], $F_C = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 with c = 0 with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c = 0 [8,10], $c = \kappa |z_s|$ with c =

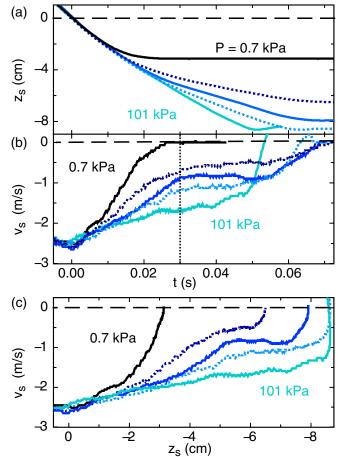


FIG. 2 (color online). (a) Sphere depth z_s versus time after impact (t=0 s). (b) Velocity $v_s(t)$ computed from curves in (a). (c) Velocity $v_s(z_s)$ versus depth. All panels top to bottom: P=0.7, 4.9, 8.7, 12, and 101 kPa.

projectile and thus a z_s dependence of its velocity over the whole range from impact to final stop.

The data in Fig. 2 for intermediate pressures reveal a feature not captured in these models: a region of near-constant velocity beginning roughly 30 ms after the impact (dotted vertical line). This behavior can be seen most clearly when the velocity is plotted as function of depth z_s below the free surface [Fig. 2(c)]. A second important feature is the rapid deceleration *after* the constant velocity regime, seen clearly in the traces for P = 4.9 kPa and 8.7 kPa. It is nearly as abrupt as when the sphere hits the bottom of the container (see traces for higher pressures), but occurs here sufficiently far inside the bed for boundary effects to be irrelevant [25]. As we show below, these characteristic features are closely linked to the interplay between penetrating sphere, bed particles, and interstitial gas.

X-ray radiography allows us to examine this interplay locally. In Fig. 3, we plot the change in local packing fraction, $\Delta \phi = \phi - \phi_0$, measured along the centerline of the path of the sphere, at three different depths, z_m below the surface. At P=0.7 kPa there is a clear jump in $\Delta \phi$ well before the sphere arrives. With increasing depth this jump occurs further ahead of the sphere, demonstrating that the compacted region grows as the sphere plows into grains that do not flow out of the way. The situation is quite different at P=101 kPa. The packing fraction remains constant except for a slow upturn once the sphere comes within about half its diameter of z_m . The width of this small compaction front varies little with depth. The overall magnitude of compaction decreases smoothly with increasing pressure [Fig. 4(b)].

A global measure of the effect of interstitial gas is the rise of the top surface as the sphere burrows into the bed. This rise can be seen in Figs. 1(a)-1(c) but is considerably reduced when the system is evacuated [Figs. 1(d)-1(f)]. In Fig. 4(a) we track the level change δh of the top surface for different pressures. At impact, the bed rapidly rises, then at time t_m [highlighted for 101, 8.7, and 0.7 kPa by arrows in Fig. 4(a)] levels off into a broad maximum of height $\delta h_{\rm max}$ and eventually falls to a final level $\delta h < 0$ (at 101 kPa this final settling does not occur until times much later than

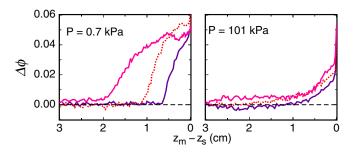


FIG. 3 (color online). Compaction front preceding sphere. Change in packing fraction $\Delta \phi$ measured along the path of the sphere at depths (left to right) $z_m = 1.0$, 2.0, and 3.0 cm plotted against distance from sphere tip z_s to z_m .

shown). The change in height $\delta h_{\rm max}$ increases with pressure, suggesting that the interstitial gas makes the bed as a whole less compressible and more fluidlike.

To check this, we use x-ray images as in Fig. 1 to track the shape of the cavity and estimate its volume, assuming cylindrical symmetry. For atmospheric pressure we find that $\delta h(t)$ corresponds, within experimental uncertainties, to what would be expected from an incompressible fluid. With decreasing P the level $\delta h_{\rm max}$ drops below the value obtained from the cavity volume [double-sided arrows in Fig. 4(a)], indicating a less elastic response.

We can characterize the elasticity of the bed by comparing the gravitational energy gained by the bed ΔU_b to the kinetic energy lost by the sphere ΔK_s in time t_m . While at P=0.7 kPa only 0.1% of the impacting sphere's energy is transferred to the bed, this value increases to about 45% at atmospheric pressure [Fig. 4(b)]. This can be compared to values around 10% found in 2D simulations without interstitial gas [12].

To understand the fluidlike behavior at large P, we examine the rate of gas flow through the bed. If the time scale for the expulsion of the gas from the bed is significantly longer than the time scale for the granular flow, then gas trapped and compressed by the bed can create pressure differences capable of supporting the bed [16,19-21]. From Darcy's law and the continuity equation for the gas flow, one can derive a diffusion equation for the gas pressure $(\partial P/\partial t) = D(\partial^2 P/\partial^2 z)$, with diffusion constant $D = \{kP/[\mu(1-\phi)]\}$, where μ is gas viscosity and k bed

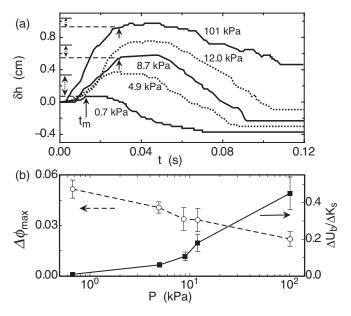


FIG. 4. Bed dynamics. (a) Rise of bed surface δh . Arrows mark t_m for three pressures. Double-sided arrows denote rise needed to conserve bed volume . Resolution of δh was limited by pixel size to ~ 0.5 mm. (b) Maximum change in packing fraction in front of sphere (\bigcirc) and ratio of potential energy needed to raise bed by $\delta h_{\rm max}$ to kinetic energy lost by sphere at time t_m (\blacksquare). Error bars for $\Delta \phi_{\rm max}$ are due to fluctuations in $\Delta \phi$, and for $\Delta U_b/\Delta K_s$ due to uncertainty in t_m .

permeability [19,20]. For our experimental conditions $D \sim 5 \text{ cm}^2/\text{s}$ at P=101 kPa. The time scale to diffuse across the depth of our bed (a distance L=8.5 cm) is $\tau_D=L^2/D\sim 140 \text{ ms}$, significantly longer than the time $t_m \sim 30 \text{ ms}$ for the bed to rise to δh_{max} . This suggests that air trapped in the bed interstices prevents compaction at large P. Since the permeability depends on the grain diameter according to $k \sim d^2$, this cushioning effect would be less pronounced with larger grains, as noted in [3]. Conversely, we expect the behavior of larger grains to resemble that found at our lowest pressures. Indeed, the trajectory of the sphere at 0.7 kPa is qualitatively similar to trajectories measured by Durian $et\ al.$ in 250–350 μ m glass spheres [6,9].

The air-mediated response of the granular bed directly affects the drag on the impacting sphere. Comparing Figs. 2(b), 2(c), and 4(a) we see that the onset of the constant velocity regime coincides with t_m , the start of the plateau in bed level rise. During this stage the material displaced by the sphere is flowing mostly into the cavity behind it. Consequently, the sphere is not affected by the full bed, but instead by a more local region. For $v_s \sim$ 1 m/s, as for our data, the drag $\phi \rho D_s^2 v_s^2$ is within a factor of 2 of the weight of the sphere. This suggests a large reduction of F_C in the force law in the observed constant velocity regime. When the top level of the bed begins to fall again, the cavity behind the sphere has pinched shut [Fig. 1(c)], trapping an air pocket below the surface [16]. With the falling bed and trapped air pocket, the bed material is no longer free to flow out of the way of the sphere. Coulomb friction is again set by the full weight of the bed, resulting in an increase in F_C that quickly decelerates the sphere and brings it to rest.

As a result, a friction term of the form $F_C = \kappa |z|$ cannot capture the full range of observed behavior, even if κ is made to depend on pressure. Such pressure dependence was very recently proposed by Cabarello et al. [17] who measured the trajectory of a sphere impacting 40 µm sand by tracking a string attached to it. Our results agree with their conclusion that the shallower penetration at lower pressures is due to increased friction. However, since $\Delta \phi > 0$ (Fig. 3) at all pressures, drag reduction is not simply due to fluidization of grains ahead of the sphere. Instead, our measurements of the local packing fraction indicate that in the presence of air the bed as a whole behaves more like an incompressible fluid, allowing the impacting sphere to penetrate deep and create a large cavity. In the absence of air the bed compacts much more strongly ahead of the sphere, rapidly dissipating energy and decelerating the descent.

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